

# RECURSIVE T-MATRIX ALGORITHMS FOR 1-D AND 2-D CLUSTERINGS OF STRIPS

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## I. INTRODUCTION

Recently, two recursive T-matrix algorithms have been introduced [1], [2], and their applications to scattering from dielectric [2] and conducting [3] scatterers have been discussed. In this paper, we will

- (1) discuss the application of these algorithms to conducting strip geometries, and
- (2) analyze the complexities of the algorithms.

The two algorithms are shown to have complexities of  $O(N^2P)$  and  $O(NP^2)$ , where  $N$  is the number of unknowns in the problem, and  $P$  is the number of terms that satisfies a convergence criterion in the addition theorems for the cylindrical wave functions.  $P$  usually depends on  $N$  through a relation

$$P \propto N^\alpha. \quad (1)$$

Clearly, determining the exact nature of this relation, i.e., determining the value of  $\alpha$  is essential since  $\alpha < 1$  implies that the recursive T-matrix algorithms have complexities less than  $O(N^3)$ . In this paper, we will show that  $\alpha$  is determined from the geometrical properties of the problem, namely, the clusterings of the unknowns (or strips) [3].

## II. 1-D CLUSTERING OF STRIPS

For a 1-D clustering of strips (see Fig. 1), we find that [3]

$$\alpha = 1 \implies P \propto N \quad (2)$$

which implies that the complexities of the two recursive T-matrix algorithms become  $O(N^3)$  in this case. However, Fig. 2 shows that, even for the 1-D clustering case, a recursive T-matrix algorithm takes less CPU time than a method-of-moments (MOM) solution, mostly due to shorter matrix-filling time. We have applied the recursive T-matrix algorithms to the electromagnetic problem of scattering from 10 strips of width  $w$  and spacing  $d = 2w$ . (see Fig. 1) This is a two-dimensional geometry for a one-dimensional finite-size frequency selective surface (FSS). Both TM (to  $y$ ) and TE (to  $y$ ) polarized incident plane waves have been considered. Figures 3(a) and 3(b) show the normalized radar cross sections (RCSs) for the TM and TE cases as a function of the angle of reflection and the frequency. The normalization is such that, for each frequency, the power radiated in the total scattered field is a constant. The frequency is specified by  $kw$  where  $k$  is the free-space wavenumber and  $w$  is the actual width of each strip. These results are checked against MOM results with excellent agreements.

## III. 2-D CLUSTERING OF STRIPS

For a 2-D clustering of strips (see Fig. 4), we find that [3]

$$\alpha = \frac{1}{2} \Rightarrow P \propto N^{1/2} \quad (3)$$

which implies that the recursive algorithms with complexities  $O(N^2P)$  and  $O(NP^2)$  perform as  $O(N^{5/2})$  and  $O(N^2)$ , respectively. Figure 5 shows a comparison of the CPU times required by a MOM solution and a recursive T-matrix algorithm for 2-D problems. Figure 6 shows the comparison of the RCSs of the geometry of Fig. 4 as obtained by a MOM solution and a recursive T-matrix algorithm.

#### REFERENCES

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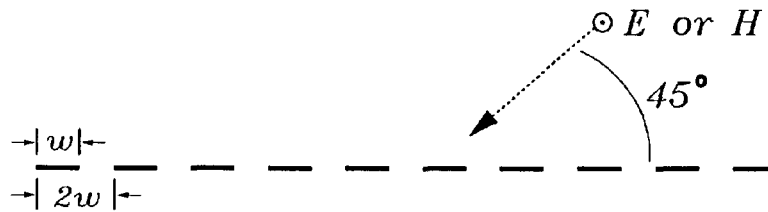


Fig. 1. TM or TE plane wave incident on a finite-size FSS of ten strips.

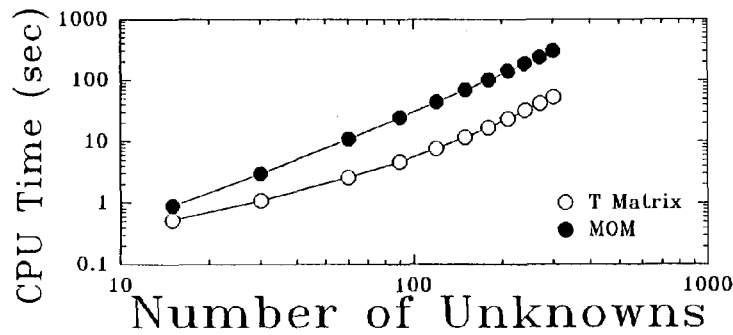
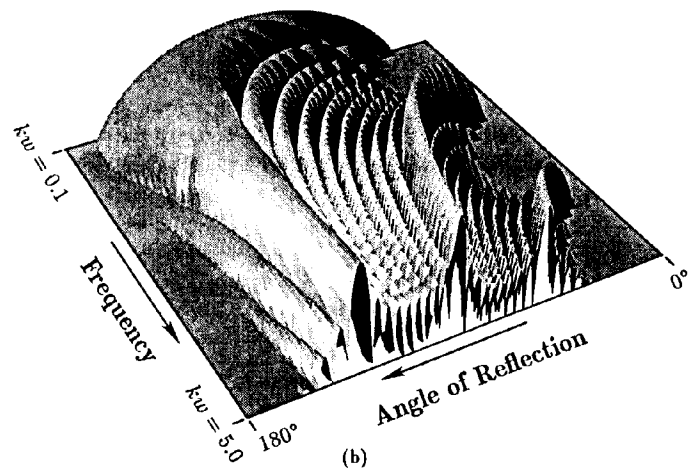
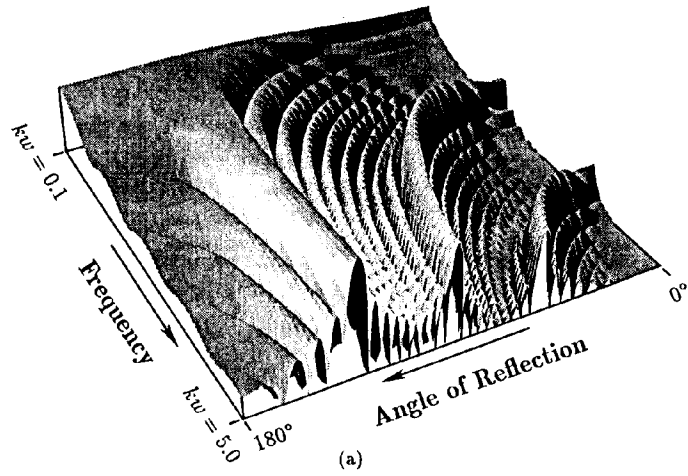


Fig. 2. Comparison of CPU times required by a MOM solution and a recursive T-matrix algorithm for a 1-D clustering case.



**Fig. 3.** Normalized RCS of the ten-strip FSS of Fig. 1 as a function of the angle of reflection and the frequency, (a) TM incidence, (b) TE incidence.

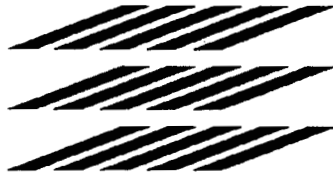


Fig. 4. An example of a 2-D clustering of strips.

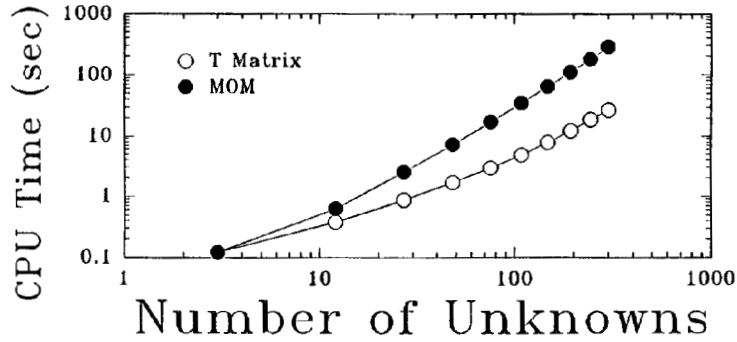


Fig. 5. Comparison of CPU times required by a MOM solution and a recursive T-matrix algorithm for a 2-D clustering case.

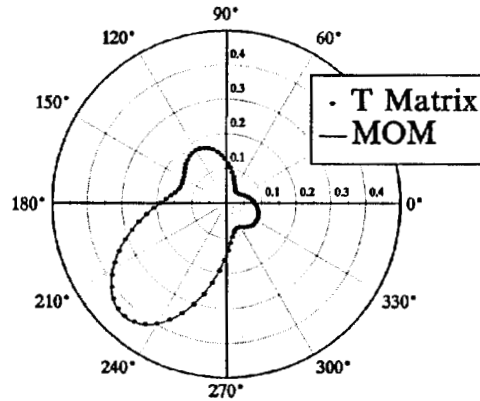


Fig. 6. Normalized RCS of 100 strips of width  $kw = 0.2$  that are clustered in two dimensions (as in Fig. 4) with horizontal spacing  $kd = 0.4$  and vertical spacing  $kh = 0.25$ . TM plane wave is incident on the strips.